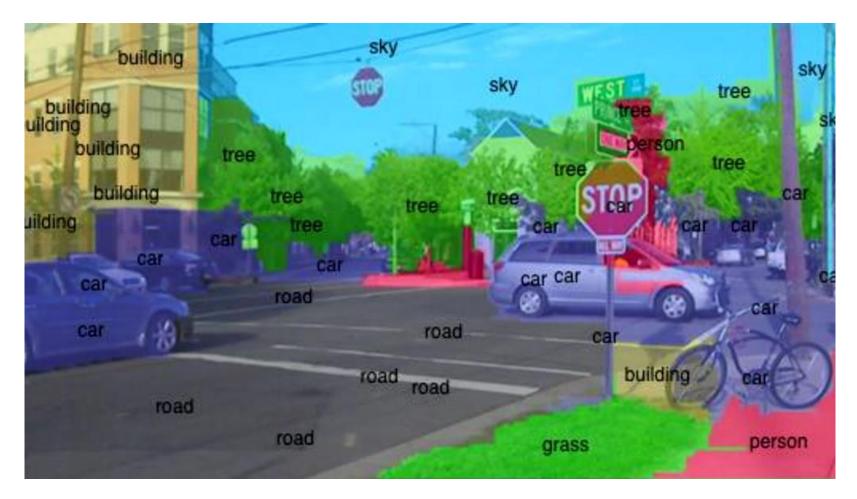
Intro to Computer Vision



Yoni Chechik

www.AlisMath.com

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- Course details
- What is computer vision (CV)?
- Course outline
- Intro to Python

References

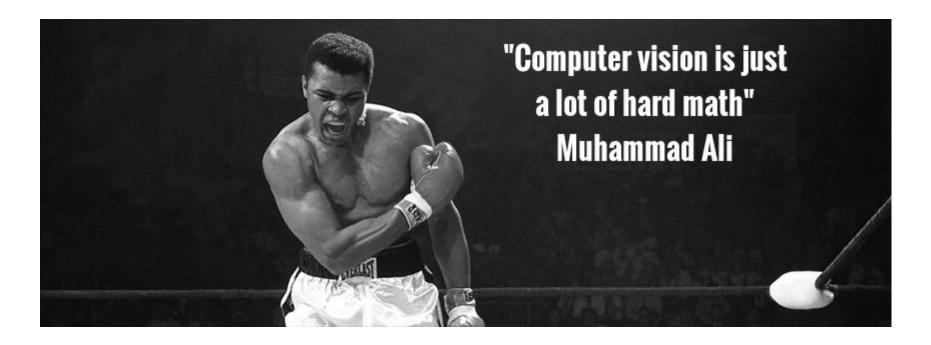
 Lectures Based on the book: Computer Vision: Algorithms and Applications, 2010, Richard Szeliski (<u>http://szeliski.org/Book/</u>)

Course objectives

- The student will know and understand key algorithms in computer vision.
- The student will be familiar with the algorithmic R&D process, with an emphasis on understanding the advantages and disadvantages of various algorithms and building an algorithmic system that concentrates on computer vision and image processing.
- The student will be able to solve algorithmic problems with computer vision both at theoretical and practical level (in Python using NumPy, Matplotlib, OpenCV & TensorFlow packages).

Prerequisites

- No prior knowledge in signal/image processing is assumed.
- Heavy use in algebra and calculus- mathematical maturity **is assumed.**

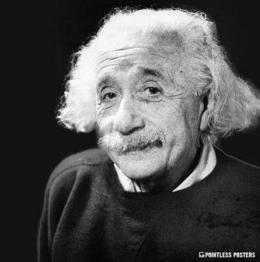


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Don't believe everything you read on the internet just because there's a picture with a quote next to it.

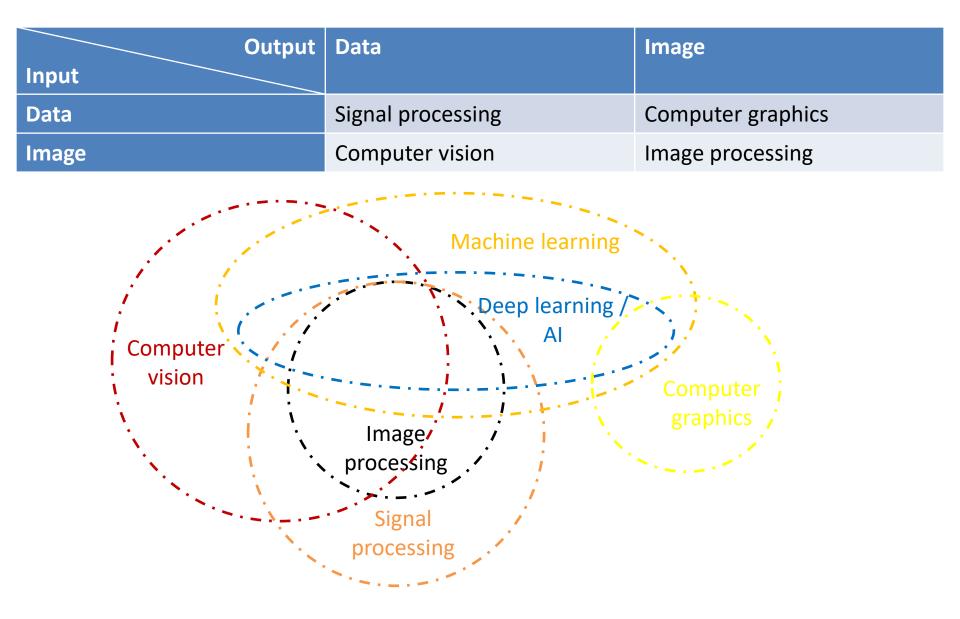
ALBERT EINSTEIN



What is CV?

- **Computer vision** is an interdisciplinary scientific field that deals with how computers can be made to gain high-level understanding from digital images or videos. [Wikipedia]
- Image processing is an umbrella term for many functions that analyze images or convert one representation of an image into another.

What is CV?

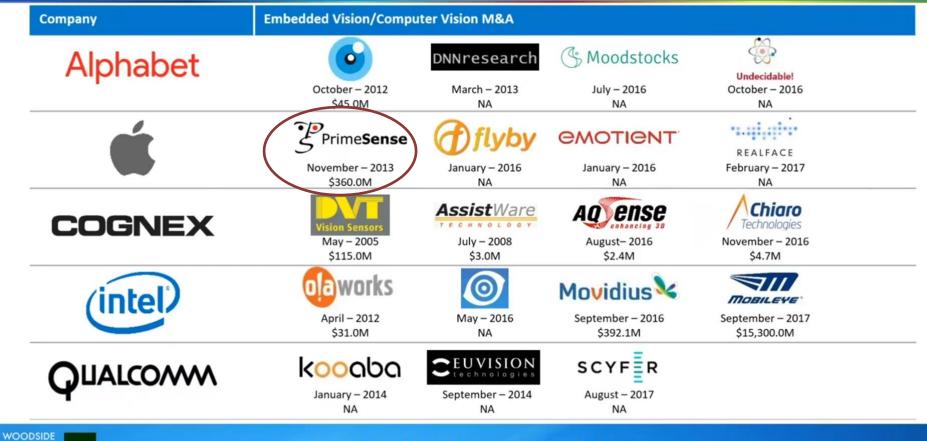


Why CV?

Top Public Company Acquirors

C A PITAL PARTNERS

WCP



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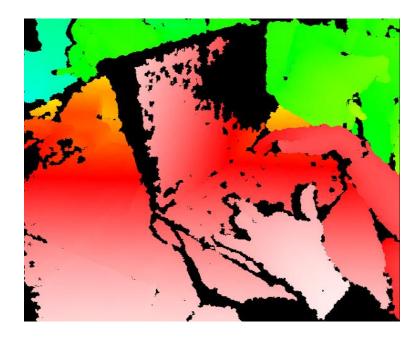
em

PrimeSense == Kinect

- Kinect for Xbox 360: 3D scanner system using Light
 Coding approach for 3D reconstruction.
- KinectFusion [Newcombe et al., 2011] : <u>https://www.youtube.com/watch?v=KOUSSIKUJ-A</u>







Why CV?

Top Public Company Acquirors

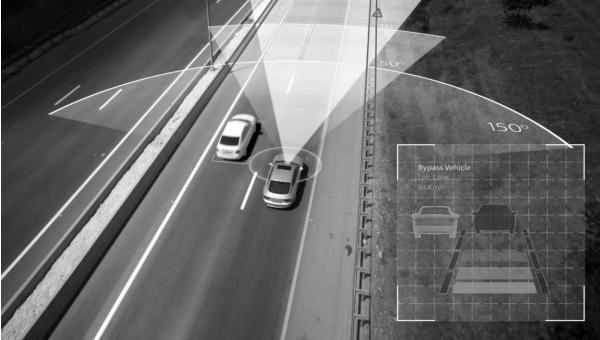
PARTNERS WCP



Company	Embedded Vision/Compu	ter Vision M&A		
Alphabet	•	DNNresearch	(Moodstocks	Undecidable!
	October – 2012 \$45.0M	March – 2013 NA	July – 2016 NA	October – 2016 NA
é	PrimeSense	 flyby	emotient	REALFACE
	November – 2013 \$360.0M	January – 2016 NA	January – 2016 NA	February – 2017 NA
COGNEX	Vision Sensors May – 2005	AssistWare	August- 2016	November – 2016
	\$115.0M	\$3.0M	\$2.4M	\$4.7M
(intel)	ojaworks	$\textcircled{\textbf{0}}$	Movidius 🔽	MOBILEYE
	April – 2012 \$31.0M	May – 2016 NA	September – 2016 \$392.1M	September – 2017 \$15,300.0M
	kooaba	CEUVISION technologies	SCYFR	
Υ	January – 2014 NA	September – 2014 NA	August – 2017 NA	

Mobileye

- Mobileye is an Israeli subsidiary of Intel corporation that develops vision-based advanced driver-assistance systems (ADAS) providing warnings for collision prevention and mitigation. [Wikipedia]
- https://www.youtube.com/watch?v=JDUb6CurYJM
- <u>https://www.youtube.com/watch?v=fKXztwtXaGo</u> (Teslacooler!)



Why CV?

StartupHub.ai

ISRAEL'S COMPUTER VISION STARTUPS



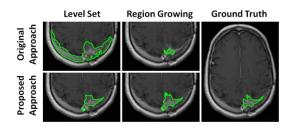


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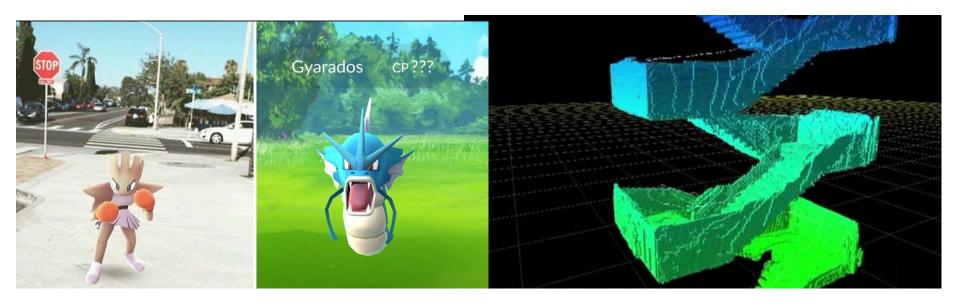
More CV related topics

- Virtual/augmented reality
- navigation
- Gaming
- medicine
- And much more...

Segmentation Results







contents

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Course outline

#	subject
1	Introduction to CV + Python: NumPy, Matplotlib, OpenCV
2	Image processing recap: convolutions, LPF, HPF, morphology, connected components, gamma correction, decimation, interpolation.
3	Edge detection: gradient (roberts, prewitt, sobel), Laplacian, DoG (derivative of Gaussian), canny edge detector.
4	Curve fitting: least squares, total least squares, RANSAC, Hough transform.
5	Image formation: BRDF, pinhole camera, digital camera
6	Geometric transformation: 2d->2d, 3d->3d, 3d->2d (perspective and homographic projection)
7	Camera calibration: extrinsic, intrinsic, radial distortion.
8	Stereo vision: dual camera rectification, triangulation.
9	Features: feature detection, feature description, matching, SIFT, panoramas.
10	Stereo: SfM, Epipolar geometry, rectification, triangulation, matching.
11	Neural networks 1: intro, perceptron, dense layers, MNIST.
12	Neural Networks 2: CNN, back-propagation, tensorflow.

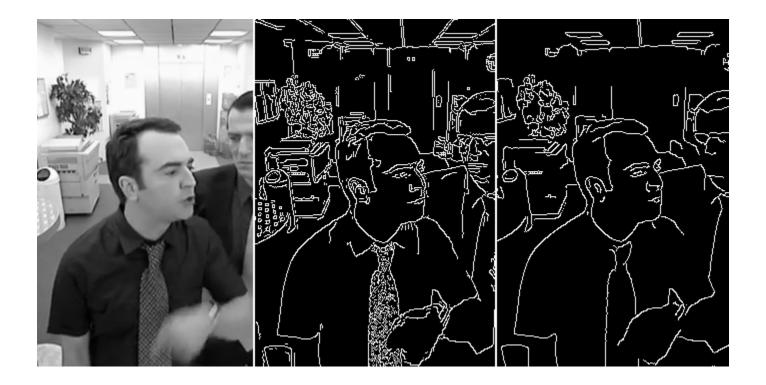
Image processing

 Read more about Lenna – the standard test image: <u>https://en.wikipedia.org/wiki/Lenna</u>

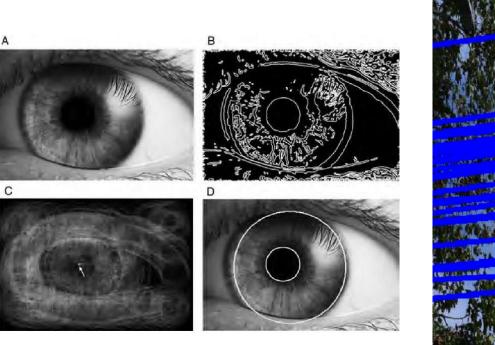


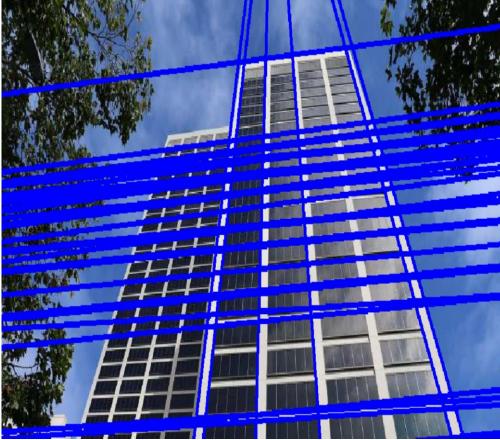
Edge Detection

- https://www.youtube.com/watch?v=hQ-bpfdWQh8
- <u>https://pinetools.com/image-edge-detection</u>



Curve fitting & Hough transform





Digital cameras

- Image formation: <u>https://www.youtube.com/watch?v=dY0K65eXhkA</u>
- 2D & 3D transformation.





from Hartley & Zisserman

Image calibration

• Fisheye correction from go-pro for example



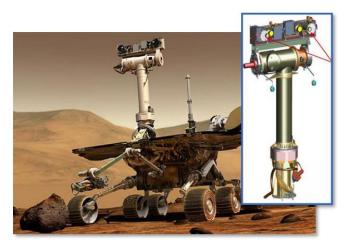
Stereo & 3d cameras

https://www.youtube.com/watch?v=PySBQ8Q_R8k





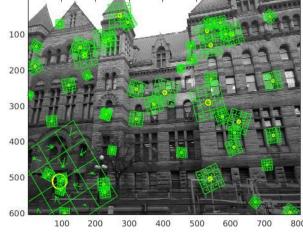






Features

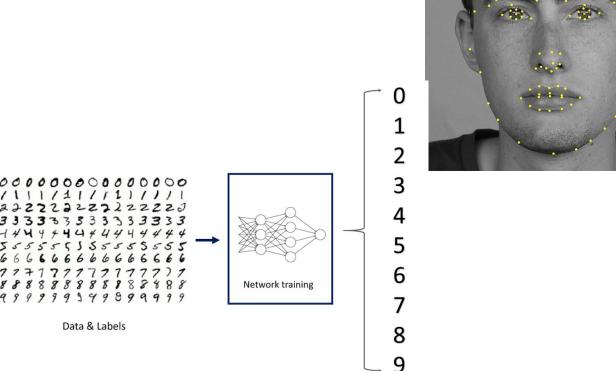
- Extract interesting points from image for later recognition, stitching, learning and more.
- http://www.in2white.com/

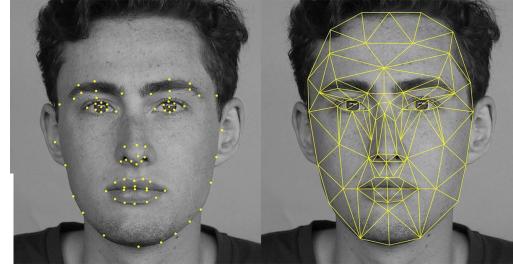




Neural networks

- <u>https://deepdreamgenerator.com/generator</u>
- <u>https://quickdraw.withgoogle.com</u>





Dream generator- style transfer



Dream generator- style transfer



And some more AI stuff

- Deep fake
 - <u>https://www.youtube.com/watch?v=cQ54GDm1eL0</u>
 - <u>https://www.youtube.com/watch?v=-QvIX3cY4lc</u>
- Nvidia GauGAN
 - <u>https://www.youtube.com/watch?v=p5U4NgVGAwg</u>
 - <u>http://nvidia-research-mingyuliu.com/gaugan</u>

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